Approximating Dense Cases of Covering Problems

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Abstract

We study dense cases of several covering problems. An instance of the set cover problem with m sets is dense if there is $\epsilon > 0$ such that any element belongs to at least ϵm sets. We show that the dense set cover problem can be approximated with the performance ratio $c \log n$ for any c > 0 and it is unlikely to be NP-hard. We construct a polynomial-time approximation scheme for the dense Steiner tree problem in n-vertex graphs, i.e. for the case when each terminal is adjacent to at least ϵn vertices. We also study the vertex cover problem in ϵ -dense graphs. Though this problem is shown to be still MAX-SNP-hard as in general graphs, we find a better approximation algorithm with the performance ratio $\frac{2}{1+\epsilon}$. The superdense cases of all these problems are shown to be solvable in polynomial time.

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1 Dense Set Cover Problem

We start with the Dense Set Cover Problem. Let $X = \{x_1, ..., x_k\}$ be a finite set and $P = \{p_1, ..., p_m\} \subseteq 2^X$ be a family of its subsets. The Set Cover Problem (SCP) asks for a minimum size sub-family M of P such that $X \subseteq \bigcup \{p | p \in M\}$.

The greedy heuristic gives 1 + lnk approximation for SCP [5]. Moreover, SCP cannot be approximated to within less than $\ln k$ -factor unless $NP \subseteq DTIME[n^{loglogn}]$ [6].

The *B*-sparse SCP has a constant upper bound B > 1 on the number of sets in *P* which cover the same element of *X*. The Vertex Cover Problem is a wellknown representative of *B*-sparse SCP (B=2). There is a simple *B*-approximation algorithm for this problem. From the other side, the *B*-sparse SCP is MAX SNPcomplete.

In an ϵ -dense SCP, any element of X belongs to at least $\epsilon |P|$ sets for some $\epsilon < 1$.

We will analyze the greedy heuristic applied to ϵ -dense SCP. This heuristic repeatedly choose a maximum size set in P, remove its elements from X and all other sets in P. All chosen sets form the output set cover *Greedy*.

Lemma 1 The size of Greedy is at most $\log_{1/(1-\epsilon)} k$.

Proof. At first we will show that the maximum size of a set in P is at least ϵk . Consider a bipartite graph $G = (P \cup X, E)$ where $x \in X$ and $p \in P$ are adjacent if and only if $x \in p$. The degree of any $x \in X$ is at least ϵm , so the number of edges in this graph is at least $\epsilon m k$ and, therefore, there is a set $p \in P$ with degree at least ϵm .

Each iteration of the greedy heuristic does not decrease density, since all elements which belong to the chosen set are removed from X. So the size of X after the *i*th iteration is at most $(1 - \epsilon)^i k \diamondsuit$

This lemma shows that the size of the optimal set cover is $O(\log k)$. So we cannot expect that the ϵ -dense SCP is NP-complete, since a simple $O(m^{O(\log k)})$ -time exhaustive search chooses the optimal solution.

Theorem 1 Unless $NP \subseteq DTIME[n^{\log n}]$, the ϵ -dense SCP is not NP-complete.

Note that $O(\log k)$ is the tight bound for the performance ratio of the greedy heuristic applied to ϵ -dense SCP. To show this for $\epsilon = \frac{1}{2}$, we can construct an instance of this problem with the size of optimal solution of $O(\log k)$ and then add two sets A and B such that $A \cup B = X$, $A \cap B = \emptyset$. On the other hand, unlike to the general case of SCP, we may decrease the constant factor as far as we want.

Lemma 2 For any c > 0 and $1 > \epsilon > 0$, there is a $c \ln k$ -approximation algorithm for ϵ -dense SCP.

Proof. Indeed, let transform an instance of ϵ -dense SCP to an instance of $(1 - (1 - \epsilon)^2)$ -dense SCP in the following way. Consider a family $P^2 = \{p \cup q : p, q \in P\}$. It is easy to see that any solution for SCP with the family P^2 gives a solution for initial SCP. An ϵ -density means that at most $(1 - \epsilon)m$ sets do not contain a given element of X. But then at most $(1 - \epsilon)^2m^2$ sets in P^2 do not contain a given element of X.

Lemma 1 implies that such transformation decrease the performance ratio of the greedy algorithm twice. \diamondsuit

Theorem 1 arises the following two open problems:

Problem 1 Can ϵ -dense SCP be solved in polynomial time?

Problem 2 Can ϵ -dense SCP be approximated in polynomial time to within constant factor?

Further densification leads to polynomial solvability of SCP. The δ -superdense SCP is the case of SCP where each element of X is covered by at least $m - o(m^{\delta})$ sets of P for some $\delta < 1$.

Theorem 2 The δ -superdense SCP can be solved in polynomial time.

Proof. Let each element of X is covered by at least $m - \gamma m^{\delta} = m(1 - \gamma m^{\delta-1})$ sets of P for some $\gamma < m^{1-\delta}$. By Lemma 1 for $\epsilon = 1 - \gamma m^{\delta-1}$, the size of optimal solution is at most

$$\log_{\gamma^{-1}m^{1-\delta}} k = \frac{1}{(1-\delta)(1-\log_m \gamma)} \log_m k.$$

Thus, exhaustive search for finding an exact solution has at most $k^{((1-\delta)\delta)^{-1}}$ cases to consider. \diamond

2 Dense Steiner Tree Problem

Consider a connected graph G = (V, E) with a *terminal* set $S \subseteq V$. The Steiner Tree Problem (STP) asks for a minimum size tree within G which spans all terminals from S. Further, d(F) denotes the length of a graph F, |S| = k and |V| = n. A well-known minimum spanning tree heuristic (MSTH) [9] finds a minimum spanning tree M of a weighted complete graph G' = (S, E', c), where the weight of any edge equals to the length of the shortest path between its ends in G. Then MSTH replaces all edges of M with the corresponding paths in G and extracts a tree from the subgraph obtained.

An optimal Steiner tree contains also non-terminals. Each such vertex of degree at least 3 is called a *Steiner point*. It is easy to see that there are at most k-2 Steiner points. Using MSTH we can find an optimal Steiner tree if we add all Steiner points to the terminal set.

Remark 1 An optimal Steiner tree can be found exactly in $O(n^k)$ time.

MSTH gives 2-approximation for STP [9] and the best up-today polynomialtime approximation guarantee is about 1.644 [7]. From the other side, STP is known to be MAX SNP - complete [4].

In the *B*-sparse STP the degree of any vertex is bounded by a constant B. It is known that STP in the rectilinear metric (a sub-case of 4-sparse STP) is NP-complete but the question whether it is MAX SNP-hard or not is still open.

In an ϵ -dense instance of STP (for some $\epsilon < 1$) any terminal has at least ϵn neighbors outside S.

Note that for $\epsilon > \frac{1}{2}$, ϵ -dense STP is a sub-case of Network STP with distances 1 and 2 which is still MAX SNP-complete [4]. The Rayward-Smith heuristic [8] was proposed for the latter problem in [4]. It achieves a better approximation guarantee $(\frac{4}{3})$ then MSTH which has the tight bound 2 as for the general case. MSTH also does not differ the dense and general case of STP.

If the number of terminals is small enough, i.e. $k \leq \frac{1}{\epsilon}$, then we can find an exact solution in polynomial time. Otherwise, we apply to the dense STP the following variant of Rayward-Smith heuristic (or the greedy algorithm [10]).

Algorithm DSTP

Let C consist of sets $C_1, ..., C_r$ after Step (1) of Algorithm DSTP. Let add edges between all terminals of the same set $C_i, i = 1, ..., r$. The length of the optimal Steiner tree in the graph G' obtained cannot be longer than in G. There is an optimal Steiner tree OPT' in G' containing spanning trees M_i for each set $C_i, i = 1, ...r$. If we contract any such tree M_i to a vertex, then OPT' appears to be an optimal Steiner tree M_0 spanning vertices corresponding to C_i . Thus, the edge set of OPT' is a union of edges of $M_i, i = 0, 1, ..., r$.

Algorithm DSTP constructs some Steiner trees M'_i in G for terminals of C_i (step (1)) and then finds the shortest tree M'_0 spanning M'_i , i = 1, ..., r (step (2)). M'_0 cannot be longer that M_0 , since M_0 also spans M'_i . Remark 1 implies that an exhaustive search in Step (2) can be executed in time $O(n^{1/\epsilon})$.

An approximation ratio of Algorithm DSTP is at most

$$\frac{\sum_{i=0}^{r} d(M_i')}{\sum_{i=0}^{r} d(M_i)} \le \frac{\sum_{i=1}^{r} d(M_i')}{\sum_{i=1}^{r} d(M_i)} = \frac{k-r+|SP|}{k-r} \le 1 + \frac{|SP|}{k-\frac{1}{\epsilon}}.$$
(1)

The size of SP equals to the number of iterations in Step (1). Each iteration of (1) decreases the size of \mathcal{C} by at least $\epsilon |\mathcal{C}| - 1$. Thus, after *i*-th iteration $|\mathcal{C}| \leq (k - \frac{1}{\epsilon})(1 - \epsilon)^i + \frac{1}{\epsilon}$. The procedure (1) interrupts when $|\mathcal{C}| < \frac{1}{\epsilon} + 1$, so

$$|SP| \le \log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon}).$$

Thus, (1) implies the following

Lemma 3 An approximation ratio of Algorithm DSTP is at most

$$1 + \frac{\log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon})}{k - \frac{1}{\epsilon}} \diamondsuit$$

Given an arbitrary approximation ratio $1 + \gamma$, $\gamma > 0$, our strategy is to solve exactly in polynomial time (for fixed ϵ and γ) instances of DSTP with small number of terminals, i.e. when k satisfies the following inequality

$$\frac{\log_{1/(1-\epsilon)}(k-\frac{1}{\epsilon})}{k-\frac{1}{\epsilon}} \le \gamma.$$

If the number of terminals is sufficiently big, then we apply Algorithm DSTP. Thus we obtain the following

Theorem 3 There is a polynomial-time approximation scheme for the ϵ -dense STP. \diamond

It is not difficult to see that there is a polynomial time reduction of the ϵ dense SCP to the ϵ -dense STP and vice versa, thus, the problem of polynomial time solvability of ϵ -dense STP is equivalent to Problem 1.

Similarly to SCP, we define δ -superdense STP to be the case of STP where any terminal has at least $n - o(n^{\delta})$ neighbors outside S.

Corollary 1 The δ -superdense STP can be solved exactly in polynomial time.

3 Dense Vertex Cover Problem

Vertex Cover Problem (VCP). Given a graph G = (V, E), find a minimum size vertex set $OPT \subseteq V$ such that at least one end of any edge belongs to OPT.

The following algorithm is suggested for VCP in ϵ -dense graphs, i.e., in graphs where any vertex has at least ϵn neighbors for some $\epsilon > 0$ (|V| = n). Let O(v)denote the set of neighbors of a vertex v, G(V') denote a subgraph induced by a vertex set $V' \subseteq V$ and 2VC denote the well-known 2-approximation algorithm for VCP.

Algorithm DVC

for all $v \in V$ do $V' \leftarrow V \setminus (O(v) \cup \{v\})$; find a vertex cover VC(v) for G(V') using 2VC; $VC(v) \leftarrow O(v) \cup VC(v)$; $APPR \leftarrow arg \min_{v \in V} |VC(v)|$.

Let $v \notin OPT$. Then $O(v) \subseteq OPT$ since all edges incident to v should be covered by OPT. Moreover, O(v) covers all edges between O(v) and the corresponding V'. So the rest of vertices of OPT cover the edges of G(V').

Let OPT' = OPT - O(v). The output vertex cover of 2VC applied to V' has a size at most min $\{2|OPT'|, |V'|\}$. So the approximation ratio can be bounded as follows.

$$\frac{|APPR|}{|OPT|} \le \frac{|O(v)| + \min\{2|OPT'|, |V'|\}}{|O(v)| + |OPT'|} \le \min\{\frac{|O(v)| + 2|OPT'|}{|O(v)| + |OPT'|}, \frac{n}{|O(v)| + |OPT'|}\}$$

If $2|OPT'| \leq (1-\epsilon)n$, then

$$\frac{|APPR|}{|OPT|} \le \frac{\epsilon n + 2|OPT'|}{\epsilon n + |OPT'|} = 2 - \frac{1}{1 + \frac{|OPT'|}{\epsilon n}}$$

Thus, the more |OPT'| corresponds to the more bound for the approximation ratio. Therefore,

$$\frac{|APPR|}{|OPT|} \le 2 - \frac{1}{1 + \frac{0.5(1-\epsilon)n}{\epsilon n}} = \frac{2}{1+\epsilon}.$$

If $2|OPT'| \ge (1-\epsilon)n$, then we obtain the same bound for the approximation ratio as follows

$$\frac{|APPR|}{|OPT|} \le \frac{n}{\epsilon n + 0.5(1 - \epsilon)n} = \frac{2}{1 + \epsilon}.$$

Theorem 4 The algorithm DVC has an approximation ratio at most $\frac{2}{1+\epsilon}$ for ϵ -dense graphs.

Theorem 5 The ϵ -dense Vertex Cover Problem is MAX SNP-hard.

Proof. (Sketch.) Starting with an instance of the Vertex Cover Problem in a graph G with n vertices we dencify it joining all vertices of a clique of size $\frac{\epsilon}{1-\epsilon}n$ with all vertices of G. The resulting graph is ϵ -dense and, therefore, if we have an α -approximation for DVC, then the reduction above gives $\alpha(1+\epsilon)$ -approximation algorithm for the general problem which is MAX SNP-hard. \diamond

Further densification (as for SCP and STP) leads to decreasement of approximation complexity.

We say that an instance of VCP is δ -superdense if the degree of any vertex is at least $n - o(n^{\delta})$. Theorem 4 implies

Corollary 2 The δ -superdense VCP has a polynomial-time approximation scheme.

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